



Letter to the Editor

# The recovery of complex sparse signals from few phaseless measurements

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## ABSTRACT

We study the stable recovery of complex  $k$ -sparse signals from as few phaseless measurements as possible. The main result is to show that one can employ  $\ell_1$  minimization to stably recover complex  $k$ -sparse signals from  $m \geq O(k \log(n/k))$  complex Gaussian random quadratic measurements with high probability. To do that, we establish that Gaussian random measurements satisfy the restricted isometry property over rank-2 and sparse matrices with high probability. This paper presents the first theoretical estimation of the measurement number for stably recovering complex sparse signals from complex Gaussian quadratic measurements.

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## 1. Introduction

### 1.1. Sparse phase retrieval

Suppose that  $\mathbf{x}_0 \in \mathbb{F}^n$  is a  $k$ -sparse signal, i.e.,  $\|\mathbf{x}_0\|_0 \leq k$ , where  $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$ . We are interested in recovering  $\mathbf{x}_0$  from

$$y_j = |\langle \mathbf{a}_j, \mathbf{x}_0 \rangle|^2 + w_j, \quad j = 1, \dots, m,$$

where  $\mathbf{a}_j \in \mathbb{F}^n$  is a measurement vector and  $w_j \in \mathbb{R}$  is the noise. This problem is called *sparse phase retrieval* [2,9,12]. Let  $\mathcal{A} : \mathbb{F}^{n \times n} \rightarrow \mathbb{R}^m$  be a linear map which is defined as

$$\mathcal{A}(X) = (\mathbf{a}_1^* X \mathbf{a}_1, \dots, \mathbf{a}_m^* X \mathbf{a}_m),$$

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where  $X \in \mathbb{F}^{n \times n}$ ,  $\mathbf{a}_j \in \mathbb{F}^n$ ,  $j = 1, \dots, m$ . By abuse of notation we set

$$\mathcal{A}(\mathbf{x}) := \mathcal{A}(\mathbf{x}\mathbf{x}^*) = (|\langle \mathbf{a}_1, \mathbf{x} \rangle|^2, \dots, |\langle \mathbf{a}_m, \mathbf{x} \rangle|^2),$$

where  $\mathbf{x} \in \mathbb{F}^n$ . We also set

$$\tilde{\mathbf{x}}_0 := \{c\mathbf{x}_0 : |c| = 1, c \in \mathbb{F}\}.$$

The aim of sparse phase retrieval is to recover  $\tilde{\mathbf{x}}_0$  from noisy measurements  $\mathbf{y} = \mathcal{A}(\mathbf{x}_0) + \mathbf{w}$ , with  $\mathbf{y} = (y_1, \dots, y_m)^T \in \mathbb{R}^m$  and  $\mathbf{w} = (w_1, \dots, w_m)^T \in \mathbb{R}^m$ . One question in sparse phase retrieval is: *how many measurements  $y_j$ ,  $j = 1, \dots, m$ , are needed to stably recover  $\tilde{\mathbf{x}}_0$ ?* For the case  $\mathbb{F} = \mathbb{R}$ , in [5], Eldar and Mendelson established that  $m = O(k \log(n/k))$  Gaussian random quadratic measurements are enough to stably recover  $k$ -sparse signals  $\tilde{\mathbf{x}}_0$ . For the complex case, Iwen, Viswanathan and Wang suggested a two-stage strategy for sparse phase retrieval and show that  $m = O(k \log(n/k))$  measurements can guarantee the stable recovery of  $\tilde{\mathbf{x}}_0$  [7]. However, the strategy in [7] requires the measurement matrix to be written as a product of two random matrices. Hence, it still remains open whether one can stably recover arbitrary complex  $k$ -sparse signal  $\tilde{\mathbf{x}}_0$  from  $m = O(k \log(n/k))$  Gaussian random quadratic measurements. One of the aims of this paper is to confirm that  $m = O(k \log(n/k))$  Gaussian random quadratic measurements are enough to guarantee the stable recovery of arbitrary complex  $k$ -sparse signals. In fact, we do so by employing  $\ell_1$  minimization.

### 1.2. $\ell_1$ minimization

Set  $A := (\mathbf{a}_1, \dots, \mathbf{a}_m)^T \in \mathbb{F}^{m \times n}$ . One classical result in compressed sensing is that one can use  $\ell_1$  minimization to recover  $k$ -sparse signals, i.e.,

$$\operatorname{argmin}_{\mathbf{x} \in \mathbb{F}^n} \{\|\mathbf{x}\|_1 : A\mathbf{x} = A\mathbf{x}_0\} = \mathbf{x}_0,$$

provided that the measurement matrix  $A$  meets the RIP condition [4]. Recall that a matrix  $A$  satisfies the  $k$ -order RIP condition with RIP constant  $\delta_k \in [0, 1)$  if

$$(1 - \delta_k)\|\mathbf{x}\|_2^2 \leq \|A\mathbf{x}\|_2^2 \leq (1 + \delta_k)\|\mathbf{x}\|_2^2$$

holds for all  $k$ -sparse vectors  $\mathbf{x} \in \mathbb{F}^n$ . Using tools from probability theory, one can show that Gaussian random matrices satisfy the  $k$ -order RIP with high probability provided  $m = O(k \log(n/k))$  [1].

Naturally, one is interested in employing  $\ell_1$  minimization for sparse phase retrieval. We consider the following model:

$$\operatorname{argmin}_{\mathbf{x} \in \mathbb{F}^n} \{\|\mathbf{x}\|_1 : |A\mathbf{x}| = |A\mathbf{x}_0|\}. \quad (1.1)$$

Although the constrained conditions in (1.1) are non-convex, the model (1.1) is more amenable to algorithmic recovery. In fact, algorithms have been developed for solving (1.1) [9,15,16]. For the case  $\mathbb{F} = \mathbb{R}$ , the performance of (1.1) was studied in [11,6,13,8]. Particularly, in [11], it was shown that if  $A \in \mathbb{R}^{m \times n}$  is a random Gaussian matrix with  $m = O(k \log(n/k))$ , then

$$\operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} \{\|\mathbf{x}\|_1 : |A\mathbf{x}| = |A\mathbf{x}_0|\} = \pm\mathbf{x}_0$$

holds with high probability. The methods developed in [11] heavily depend on  $A\mathbf{x}_0$  is a *real* vector and one still does not know the performance of  $\ell_1$  minimization for recovering complex sparse signals. As mentioned

in [11]: “The extension of these results to hold over  $\mathbb{C}$  cannot follow the same line of reasoning”. In this paper, we extend the result in [11] to the complex case by employing a new idea on the RIP of quadratic measurements.

### 1.3. Our contribution

In this paper, we study the performance of  $\ell_1$  minimization for recovering complex sparse signals from phaseless measurements  $\mathbf{y} = \mathcal{A}(\mathbf{x}_0) + \mathbf{w}$ , where  $\|\mathbf{w}\|_2 \leq \epsilon$ . Particularly, we focus on the model

$$\min_{\mathbf{x} \in \mathbb{C}^n} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{x}) - \mathbf{y}\|_2 \leq \epsilon. \tag{1.2}$$

Although the constrained conditions in (1.2) are non-convex, Many numerical experiments were made to demonstrate empirical success of the proposed algorithms. For example, in [9], Moravec, Romberg, and Baraniuk proposed an iterative projection algorithm to solve the noiseless version of (1.2). Furthermore, the ADM algorithm for solving (1.2) was introduced in [16]. However, there are very few results about the theoretical performance of the model.

Our main idea is to lift (1.2) to recover rank-one and sparse matrices, i.e.,

$$\min_{X \in \mathbb{H}^{n \times n}} \|X\|_1 \quad \text{s.t.} \quad \|\mathcal{A}(X) - \mathbf{y}\|_2 \leq \epsilon, \text{rank}(X) = 1.$$

Throughout this paper, we use  $\mathbb{H}^{n \times n}$  to denote the set of Hermitian  $n \times n$ -matrices. Moreover, we require that  $\mathcal{A}$  satisfies the following restricted isometry property over low-rank and sparse matrices:

**Definition 1.1.** We say that the map  $\mathcal{A} : \mathbb{H}^{n \times n} \rightarrow \mathbb{R}^m$  satisfies the restricted isometry property of order  $(r, k)$  if there exist positive constants  $c$  and  $C$  such that the inequality

$$c\|X\|_F \leq \frac{1}{m}\|\mathcal{A}(X)\|_1 \leq C\|X\|_F \tag{1.3}$$

holds for all  $X \in \mathbb{H}^{n \times n}$  with  $\text{rank}(X) \leq r$  and  $\|X\|_{0,2} \leq k$ .

Throughout this paper, we use  $\|X\|_{0,2}$  to denote the number of non-zero rows in  $X$ . Since  $X$  is Hermitian, we have  $\|X\|_{0,2} = \|X^*\|_{0,2}$ . We next show that a Gaussian random map  $\mathcal{A}$  satisfies the RIP of order  $(2, k)$  with high probability provided  $m \gtrsim k \log(n/k)$ . Here we use  $A \gtrsim B$  to denote  $A \geq C_0 B$ , where  $C_0 \in \mathbb{R}_+$  is an absolute constant. The notation  $\lesssim$  can be defined similarly.

**Theorem 1.2.** Assume that the linear measurement  $\mathcal{A}(\cdot)$  is defined as

$$\mathcal{A}(X) = (\mathbf{a}_1^* X \mathbf{a}_1, \dots, \mathbf{a}_m^* X \mathbf{a}_m),$$

with  $\mathbf{a}_j$  independently taken as complex Gaussian random vectors, i.e.,  $\mathbf{a}_j \sim \mathcal{N}(0, \frac{1}{2}\mathbf{I}_{n \times n}) + \mathcal{N}(0, \frac{1}{2}\mathbf{I}_{n \times n})i$ . If

$$m \gtrsim k \log(n/k),$$

with probability at least  $1 - 2 \exp(-c_0 m)$ ,  $\mathcal{A}$  satisfies the restricted isometry property of order  $(2, k)$ , i.e.

$$0.12\|X\|_F \leq \frac{1}{m}\|\mathcal{A}(X)\|_1 \leq 2.45\|X\|_F,$$

for all  $X \in \mathbb{H}^{n \times n}$  with  $\text{rank}(X) \leq 2$  and  $\|X\|_{0,2} \leq k$  (also  $\|X^*\|_{0,2} \leq k$ ).

In the next theorem, we show that (1.2) can robustly recover complex  $k$ -sparse signals from phaseless measurements provided  $\mathcal{A}$  satisfies the restricted isometry property of order  $(2, 2ak)$  with  $a > 0$  being suitably chosen.

**Theorem 1.3.** *Assume that  $\mathcal{A}(\cdot)$  satisfy the RIP condition of order  $(2, 2ak)$  with RIP constant  $c, C > 0$  satisfying*

$$c - \frac{4C}{\sqrt{a}} - \frac{C}{a} > 0. \quad (1.4)$$

For any  $k$  sparse signals  $\mathbf{x}_0 \in \mathbb{C}^n$ , the solution to (1.2)  $\mathbf{x}^\#$  satisfies

$$\|\mathbf{x}^\#(\mathbf{x}^\#)^* - \mathbf{x}_0\mathbf{x}_0^*\|_F \leq C_1 \frac{2\epsilon}{\sqrt{m}}, \quad (1.5)$$

where

$$C_1 = \frac{\frac{1}{a} + \frac{4}{\sqrt{a}} + 1}{c - \frac{4C}{\sqrt{a}} - \frac{C}{a}}.$$

Furthermore, we have

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \leq 2\sqrt{2}C_1 \frac{\epsilon}{\sqrt{m}\|\mathbf{x}_0\|_2}. \quad (1.6)$$

**Remark 1.4.** According to Lemma 3.2, it obtains that

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \|\mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \sqrt{2} \frac{\|\mathbf{x}^\#(\mathbf{x}^\#)^* - \mathbf{x}_0\mathbf{x}_0^*\|_F}{\|\mathbf{x}_0\|_2} \lesssim \frac{\epsilon}{\sqrt{m}\|\mathbf{x}_0\|_2}.$$

On the other hand, we have

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \|\mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \|\mathbf{x}^\#\|_2 + \|\mathbf{x}_0\|_2 \leq \|\mathbf{x}^\#\|_1 + \|\mathbf{x}_0\|_2 \leq \|\mathbf{x}_0\|_1 + \|\mathbf{x}_0\|_2.$$

Hence, we obtain that

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \min \left\{ 2\sqrt{2}C_1 \frac{\epsilon}{\sqrt{m}\|\mathbf{x}_0\|_2}, \|\mathbf{x}_0\|_2 + \|\mathbf{x}_0\|_1 \right\}. \quad (1.7)$$

For the case where  $\|\mathbf{x}_0\|_2 + \|\mathbf{x}_0\|_1 \leq 2\sqrt{2}C_1 \frac{\epsilon}{\sqrt{m}\|\mathbf{x}_0\|_2}$ , we obtain that

$$\begin{aligned} 2\sqrt{2}C_1 \frac{\epsilon}{\sqrt{m}} &\geq \|\mathbf{x}_0\|_2^2 + \|\mathbf{x}_0\|_2\|\mathbf{x}_0\|_1 \\ &\geq \|\mathbf{x}_0\|_1^2/k + \|\mathbf{x}_0\|_1^2/\sqrt{k} = \|\mathbf{x}_0\|_1^2(1/k + 1/\sqrt{k}), \end{aligned}$$

which implies  $\|\mathbf{x}_0\|_1 \leq \sqrt{2\sqrt{2}C_1} \cdot \sqrt{\epsilon} \cdot (k/m)^{1/4}$ . Noting that

$$\|\mathbf{x}_0\|_2 + \|\mathbf{x}_0\|_1 \leq 2\|\mathbf{x}_0\|_1 \leq 2\sqrt{2\sqrt{2}C_1} \cdot \sqrt{\epsilon} \cdot \left(\frac{k}{m}\right)^{1/4},$$

we obtain that

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \lesssim \min \left\{ \frac{\epsilon}{\sqrt{m} \|\mathbf{x}_0\|_2}, \sqrt{\epsilon} \cdot \left(\frac{k}{m}\right)^{1/4} \right\}.$$

**Remark 1.5.** For  $\|\mathbf{x}_0\|_2 \geq 1$ , the error bound  $\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \lesssim \frac{\epsilon}{\sqrt{m}}$  presented in Theorem 1.3 is sharp in the sense that there exists  $\mathbf{x}_0 \in \mathbb{C}^n$  and  $\mathbf{w} \in \mathbb{R}^m$  so that  $\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \gtrsim \epsilon/\sqrt{m}$  holds with a positive constant probability. Indeed, take  $\mathbf{x}_0 = (1, 0, \dots, 0)^T \in \mathbb{R}^n$  and  $\mathbf{y} = \mathcal{A}(\mathbf{x}_0) + \mathbf{w}$  with  $\mathbf{w} = (1, \dots, 1) \in \mathbb{R}^m$ . Set  $\epsilon = \sqrt{10m}$ . Assume that  $\mathbf{x}^\#$  is a solution to

$$\min_{\mathbf{x} \in \mathbb{C}^n} \|\mathbf{x}\|_1, \quad \text{s.t.} \quad \|\mathcal{A}(\mathbf{x}) - \mathbf{y}\|_2 \leq \sqrt{10m}.$$

We claim that  $\mathbf{x}^\# = \mathbf{0}$  with probability at least 1/2, which implies that

$$\|\mathbf{x}^\#(\mathbf{x}^\#)^* - \mathbf{x}_0 \mathbf{x}_0^*\|_F = 1 \gtrsim \frac{\epsilon}{\sqrt{m}}$$

holds with probability at least 1/2. To prove  $\mathbf{x}^\# = \mathbf{0}$  with probability at least 1/2, it is enough to show that  $\mathbb{P}\{\|\mathcal{A}(\mathbf{0}) - \mathbf{y}\|_2^2 \leq 10m\} \geq 1/2$ . Note that

$$\mathbb{E}(\|\mathcal{A}(\mathbf{0}) - \mathbf{y}\|_2^2) = \mathbb{E} \left( \sum_{j=1}^m (|\mathbf{a}_{j,1}|^2 + 1)^2 \right) = \mathbb{E} \left( \sum_{j=1}^m (|\mathbf{a}_{j,1}|^4 + 2|\mathbf{a}_{j,1}|^2 + 1) \right) = 5m.$$

According to the Markov inequality, we obtain that

$$\mathbb{P}\{\|\mathcal{A}(\mathbf{0}) - \mathbf{y}\|_2^2 \leq 10m\} \geq 1 - \frac{5m}{10m} = \frac{1}{2}.$$

Hence  $\mathbf{x}^\# = \mathbf{0}$  with probability at least 1/2.

According to Theorem 1.2, if  $\mathbf{a}_j, j = 1, \dots, m$  are complex Gaussian random vectors, then  $\mathcal{A}$  satisfies RIP of order  $(2, 2ak)$  with constants  $c = 0.12$  and  $C = 2.45$  with high probability provided  $m \gtrsim 2ak \log(n/2ak)$ . To guarantee (1.4) holds, it is enough to require  $a > (8C/c)^2$ . Therefore, combining Theorem 1.2 and Theorem 1.3 with  $\epsilon = 0$ , we can obtain the following corollary:

**Corollary 1.6.** *Suppose that  $\mathbf{x}_0 \in \mathbb{C}^n$  is a  $k$ -sparse signal. Assume that  $A = (\mathbf{a}_1, \dots, \mathbf{a}_m)^T$  where  $\mathbf{a}_j, j = 1, \dots, m$  is Gaussian random vectors, i.e.,  $\mathbf{a}_j \sim \mathcal{N}(0, \frac{1}{2} \mathbf{I}_{n \times n}) + \mathcal{N}(0, \frac{1}{2} \mathbf{I}_{n \times n})i$ . If  $m \gtrsim k \log(n/k)$ , then*

$$\operatorname{argmin}_{\mathbf{x} \in \mathbb{C}^n} \{\|\mathbf{x}\|_1 : |\mathbf{A}\mathbf{x}| = |\mathbf{A}\mathbf{x}_0|\} = \tilde{\mathbf{x}}_0$$

holds with probability at least  $1 - 2 \exp(-c_0 m)$ . Here  $c_0 > 0$  is an absolute constant.

## 2. Proof of Theorem 1.2

We first introduce a Bernstein-type inequality which plays a key role in our proof.

**Lemma 2.1.** [10] *Let  $\xi_1, \dots, \xi_m$  be i.i.d. sub-exponential random variables and  $K := \max_j \|\xi_j\|_{\psi_1}$ . Then for every  $\epsilon > 0$ , we have*

$$\mathbb{P} \left( \left| \frac{1}{m} \sum_{j=1}^m \xi_j - \frac{1}{m} \mathbb{E} \left( \sum_{j=1}^m \xi_j \right) \right| \geq \epsilon \right) \leq 2 \exp \left( -c_0 m \min \left( \frac{\epsilon^2}{K^2}, \frac{\epsilon}{K} \right) \right),$$

where  $c_0 > 0$  is an absolute constant.

We next introduce some key lemmas needed to prove Theorem 1.2, and then present the proof of Theorem 1.2.

**Lemma 2.2.** Assume  $z_1, z_2, z_3$  and  $z_4$  are independently drawn from  $\mathcal{N}(0, 1)$ . If  $t \in [-1, 0]$ , we have

$$\mathbb{E}|z_1^2 + z_2^2 + tz_3^2 + tz_4^2| = 2 \left( \frac{1+t^2}{1-t} \right).$$

**Proof.** When  $t = 0$ , we have  $\mathbb{E}|z_1^2 + z_2^2 + tz_3^2 + tz_4^2| = \mathbb{E}|z_1^2 + z_2^2| = 2$ . If  $t \in [-1, 0]$ , taking coordinates transformation as  $z_1 = \rho_1 \cos \theta$ ,  $z_2 = \rho_1 \sin \theta$ ,  $z_3 = \rho_2 \cos \phi$ , and  $z_4 = \rho_2 \sin \phi$ , we obtain that

$$\begin{aligned} \mathbb{E}|z_1^2 + z_2^2 + tz_3^2 + tz_4^2| &= \left( \frac{1}{2\pi} \right)^2 \int_{\mathbb{R}^4} |z_1^2 + z_2^2 + tz_3^2 + tz_4^2| \exp \left( -\frac{z_1^2 + z_2^2 + z_3^2 + z_4^2}{2} \right) dz_1 dz_2 dz_3 dz_4 \\ &= \left( \frac{1}{2\pi} \right)^2 \int_0^{2\pi} d\theta \int_0^{2\pi} d\phi \int_0^\infty \int_0^\infty \rho_1 \rho_2 |\rho_1^2 + t\rho_2^2| \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 \\ &= \int_0^\infty \int_0^\infty \rho_1 \rho_2 |\rho_1^2 + t\rho_2^2| \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 \\ &= \int_{\rho_1 > \sqrt{-t}\rho_2} \rho_1 \rho_2 (\rho_1^2 + t\rho_2^2) \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 \\ &\quad + \int_{\rho_1 \leq \sqrt{-t}\rho_2} \rho_1 \rho_2 (-t\rho_2^2 - \rho_1^2) \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 \\ &= \frac{2}{1-t} + \frac{2t^2}{1-t} = \frac{2(1+t^2)}{1-t}. \end{aligned}$$

Here, we evaluate the last integrals as follows:

$$\begin{aligned} &\int_{\rho_1 > \sqrt{-t}\rho_2} \rho_1 \rho_2 (\rho_1^2 + t\rho_2^2) \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 \\ &= \int_0^\infty \rho_2 \exp \left( -\frac{\rho_2^2}{2} \right) d\rho_2 \int_{\sqrt{-t}\rho_2}^\infty \rho_1^3 \exp \left( -\frac{\rho_1^2}{2} \right) d\rho_1 + t \int_0^\infty \rho_2^3 \exp \left( -\frac{\rho_2^2}{2} \right) d\rho_2 \int_{\sqrt{-t}\rho_2}^\infty \rho_1 \exp \left( -\frac{\rho_1^2}{2} \right) d\rho_1 \\ &= \int_0^\infty \rho_2 \exp \left( -\frac{\rho_2^2}{2} \right) \left( -t\rho_2^2 \exp \left( \frac{t\rho_2^2}{2} \right) + 2 \exp \left( \frac{t\rho_2^2}{2} \right) \right) d\rho_2 + t \int_0^\infty \rho_2^3 \exp \left( -\frac{\rho_2^2}{2} \right) \exp \left( \frac{t\rho_2^2}{2} \right) d\rho_2 \\ &= 2 \int_0^\infty \rho_2 \exp \left( -\frac{(1-t)\rho_2^2}{2} \right) d\rho_2 = \frac{2}{1-t}. \end{aligned}$$

We can use the similar method to obtain

$$\int_{\rho_1 \leq \sqrt{-t}\rho_2} \rho_1 \rho_2 (-t\rho_2^2 - \rho_1^2) \exp \left( -\frac{\rho_1^2 + \rho_2^2}{2} \right) d\rho_1 d\rho_2 = \frac{2t^2}{1-t}. \quad \square$$

**Lemma 2.3.** *Set*

$$\mathcal{X} := \{X \in \mathbb{H}^{n \times n} \mid \|X\|_F = 1, \text{rank}(X) \leq 2, \|X\|_{0,2} \leq k\}$$

which is equipped with Frobenius norm. The covering number of  $\mathcal{X}$  at scale  $\epsilon > 0$  is less than or equal to  $\left(\frac{9\sqrt{2}en}{\epsilon k}\right)^{4k+2}$ .

**Proof.** Note that

$$\mathcal{X} = \{X \in \mathbb{H}^{n \times n} : X = U\Sigma U^*, \Sigma \in \Lambda, U \in \mathcal{U}\},$$

where

$$\Lambda = \{\Sigma \in \mathbb{R}^{2 \times 2} : \Sigma = \text{diag}(\lambda_1, \lambda_2), \lambda_1^2 + \lambda_2^2 = 1\}$$

and

$$\mathcal{U} = \{U \in \mathbb{C}^{n \times 2} : U^*U = I, \|U\|_{0,2} \leq k\} = \cup_{\#T=k} \mathcal{U}_T.$$

Here  $T \subset \{1, \dots, n\}$ , and

$$\mathcal{U}_T := \{U \in \mathbb{C}^{n \times 2} : U^*U = I, U = U_{T,:}\},$$

where  $U_{T,:} \in \mathbb{C}^{n \times 2}$  is the matrix obtained by keeping the rows of  $U$  indexed by  $T$  and setting all other rows to zero. Note that  $\|U\|_F = \sqrt{2}$  for all  $U \in \mathcal{U}_T$  and that the real dimension of  $\mathcal{U}_T$  is at most  $4k$  for any fixed support  $T$  with  $\#T = k$ . We use  $Q_T$  to denote an  $\epsilon/3$ -net of  $\mathcal{U}_T$  with  $\#Q_T \leq (9\sqrt{2}/\epsilon)^{4k}$ . Then  $Q_\epsilon := \cup_{\#T=k} Q_T$  is an  $\epsilon/3$ -net of  $\mathcal{U}$  with

$$\#Q_\epsilon \leq \left(\frac{en}{k}\right)^k \left(\frac{9\sqrt{2}}{\epsilon}\right)^{4k} \leq \left(\frac{9\sqrt{2}en}{\epsilon k}\right)^{4k}.$$

We use  $\Lambda_\epsilon$  to denote an  $\epsilon/3$ -net of  $\Lambda$  with  $\#\Lambda_\epsilon \leq (9/\epsilon)^2$ .

Set

$$\mathcal{N}_\epsilon := \{U\Sigma U^* \mid U \in Q_\epsilon, \text{ and } \Sigma \in \Lambda_\epsilon\}.$$

Then for any  $X = U\Sigma U^* \in \mathcal{X}$ , there exists  $U_0\Sigma_0 U_0^* \in \mathcal{N}_\epsilon$  with  $\|U - U_0\|_F \leq \epsilon/3$  and  $\|\Sigma - \Sigma_0\|_F \leq \epsilon/3$ . So, we have

$$\begin{aligned} \|U\Sigma U^* - U_0\Sigma_0 U_0^*\|_F &\leq \|U\Sigma U^* - U_0\Sigma U^*\|_F + \|U_0\Sigma U^* - U_0\Sigma_0 U^*\|_F + \|U_0\Sigma_0 U^* - U_0\Sigma_0 U_0^*\|_F \\ &\leq \|U - U_0\|_F \|\Sigma U^*\| + \|U_0\| \|\Sigma - \Sigma_0\|_F \|U^*\| + \|U_0\Sigma_0\| \|U^* - U_0\|_F \\ &\leq \epsilon. \end{aligned}$$

Therefore,  $\mathcal{N}_\epsilon$  is an  $\epsilon$ -net of  $\mathcal{X}$  with

$$\#\mathcal{N}_\epsilon \leq \#Q_\epsilon \cdot \#\Lambda_\epsilon \leq \left(\frac{9\sqrt{2}en}{\epsilon k}\right)^{4k} (9/\epsilon)^2 \leq \left(\frac{9\sqrt{2}en}{\epsilon k}\right)^{4k+2}$$

provided that  $n \geq k$  and  $\epsilon \leq 1$ .  $\square$

We now have the necessary ingredients to prove Theorem 1.2.

**Proof of Theorem 1.2.** Without loss of generality, we assume that  $\|X\|_F = 1$ . We first consider  $\mathbb{E}\|\mathcal{A}(X)\|_1$ . Noting that  $\text{rank}(X) \leq 2$  and  $\|X\|_F = 1$ , we can write  $X$  in the form of

$$X = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^* + \lambda_2 \mathbf{u}_2 \mathbf{u}_2^*,$$

where  $\lambda_1, \lambda_2 \in \mathbb{R}$  satisfying  $\lambda_1^2 + \lambda_2^2 = 1$  and  $\mathbf{u}_1, \mathbf{u}_2 \in \mathbb{C}^n$  satisfying  $\|\mathbf{u}_1\|_2 = \|\mathbf{u}_2\|_2 = 1, \langle \mathbf{u}_1, \mathbf{u}_2 \rangle = 0$ . Therefore, we obtain that

$$\mathbf{a}_k^* X \mathbf{a}_k = \lambda_1 |\mathbf{u}_1^* \mathbf{a}_k|^2 + \lambda_2 |\mathbf{u}_2^* \mathbf{a}_k|^2,$$

where  $\mathbf{u}_1^* \mathbf{a}_k$  and  $\mathbf{u}_2^* \mathbf{a}_k$  are independently drawn from  $\mathcal{N}(0, \frac{1}{2}) + \mathcal{N}(0, \frac{1}{2})i$ . Then

$$\frac{1}{m} \|\mathcal{A}(X)\|_1 = \frac{1}{m} \sum_{j=1}^m |\lambda_1 |\mathbf{u}_1^* \mathbf{a}_j|^2 + \lambda_2 |\mathbf{u}_2^* \mathbf{a}_j|^2| = \frac{1}{m} \sum_{j=1}^m \xi_j, \quad (2.1)$$

where the  $\xi_j$  are independent copies of the following random variable

$$\xi = |\lambda_1 z_1^2 + \lambda_1 z_2^2 + \lambda_2 z_3^2 + \lambda_2 z_4^2|$$

where  $z_1, z_2, z_3, z_4 \sim \mathcal{N}(0, \frac{1}{2})$  are independent. Without loss of generality, we assume that  $|\lambda_1| \geq |\lambda_2|$  and hence  $|\lambda_1| \in [\frac{\sqrt{2}}{2}, 1]$ . Note that  $\xi$  can also be rewritten as

$$\xi = |\lambda_1| |z_1^2 + z_2^2 + t z_3^2 + t z_4^2| \quad (2.2)$$

with  $t := \lambda_2/\lambda_1$  satisfying  $|t| \leq 1$ . Since  $\frac{1}{m} \mathbb{E}\|\mathcal{A}(X)\|_1 = \mathbb{E}(\xi)$ , we first focus on  $\mathbb{E}(\xi)$ . According to (2.2), we have

$$\mathbb{E}(\xi) \leq |\lambda_1| \mathbb{E}(z_1^2 + z_2^2 + z_3^2 + z_4^2) \leq 2, \quad (2.3)$$

as  $\mathbb{E}(z_j^2) = \frac{1}{2}$  for  $j = 1, \dots, 4$ . On the other hand, when  $t \geq 0$ , we obtain that

$$\mathbb{E}(\xi) \geq |\lambda_1| \mathbb{E}(z_1^2 + z_2^2) \geq \frac{\sqrt{2}}{2}. \quad (2.4)$$

For  $t \in [-1, 0]$ , Lemma 2.2 (note the missing factor two by the slightly different variances of  $z_i$ ) shows that

$$\mathbb{E}(\xi) = |\lambda_1| \left( \frac{1+t^2}{1-t} \right) \geq 0.57. \quad (2.5)$$

Combining (2.3), (2.4) and (2.5), we obtain that

$$0.57 \leq \mathbb{E}(\xi) \leq 2.$$

Note that  $\xi$  is a sub-exponential variable with  $\|\xi\|_{\psi_1} \leq \sum_{i=1}^4 \|z_i^2\|_{\psi_1} \leq \tilde{c}$ , where  $\|\cdot\|_{\psi_1} := \sup_{p \geq 1} p^{-1} (\mathbb{E}|\cdot|^p)^{1/p}$  denotes the sub-exponential norm. We set

$$\mathcal{X} := \{X \in \mathbb{H}^{n \times n} : \|X\|_F = 1, \text{rank}(X) \leq 2, \|X\|_{0,2} \leq k\},$$



and use  $\mathcal{N}_\epsilon$  to denote an  $\epsilon$ -net of  $\mathcal{X}$  with respect to the Frobenius norm  $\|\cdot\|_F$ , i.e. for any  $X \in \mathcal{X}$ , there exists  $X_0 \in \mathcal{N}_\epsilon$  such that  $\|X - X_0\|_F \leq \epsilon$ . Based on Lemma 2.1, equality (2.1) and a union bound, we obtain that

$$0.57 - \epsilon_0 \leq \frac{1}{m} \|\mathcal{A}(X_0)\|_1 \leq 2 + \epsilon_0, \text{ for all } X_0 \in \mathcal{N}_\epsilon \tag{2.6}$$

holds with probability at least  $1 - 2 \cdot \#\mathcal{N}_\epsilon \cdot \exp(-\frac{\epsilon_0}{16} m \epsilon_0^2)$ .

Note that  $\mathcal{A}$  is continuous at  $X \in \mathcal{X}$  and  $\mathcal{X}$  is a compact set. We can set

$$U_{\mathcal{A}} := \max_{X \in \mathcal{X}} \frac{1}{m} \|\mathcal{A}(X)\|_1.$$

For any  $X \in \mathcal{X}$ , there exists  $X_0 \in \mathcal{N}_\epsilon$  such that  $\|X - X_0\|_F \leq \epsilon$  and  $\|X - X_0\|_{0,2} \leq k$ . Without loss of generality, assume that  $\text{supp}(X - X_0) \subset [1:k] \times [1:k]$  where  $[1:k] := [1, k] \cap \mathbb{Z}$ . Note that  $\text{rank}(X - X_0) \leq 4$ . We can use the eigenvalue decomposition to obtain that  $(X - X_0)_{[1:k] \times [1:k]} = U \Sigma U^*$  with  $U \in \mathbb{C}^{k \times 4}$ , and  $\Sigma = \text{diag}(\lambda_1, \dots, \lambda_4)$ . Take  $\Sigma_1 = \text{diag}(\lambda_1, \lambda_2, 0, 0)$  and  $\Sigma_2 = \text{diag}(0, 0, \lambda_3, \lambda_4)$ . Then  $X - X_0 = X_1 + X_2$  where  $X_1 = \begin{bmatrix} U \Sigma_1 U^* & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \in \mathbb{H}^{n \times n}$  and  $X_2 = \begin{bmatrix} U \Sigma_2 U^* & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \in \mathbb{H}^{n \times n}$ . If  $X_1 = \mathbf{0}$  or  $X_2 = \mathbf{0}$ , we have  $\text{rank}(X - X_0) \leq 2$ , and

$$\frac{1}{m} \|\mathcal{A}(X - X_0)\|_1 \leq U_{\mathcal{A}} \epsilon.$$

Otherwise,  $\frac{X_1}{\|X_1\|_F}, \frac{X_2}{\|X_2\|_F} \in \mathcal{X}$  and  $\langle X_1, X_2 \rangle = \langle \Sigma_1, \Sigma_2 \rangle = 0$ . Therefore, we can obtain that

$$\begin{aligned} \frac{1}{m} \|\mathcal{A}(X - X_0)\|_1 &= \frac{1}{m} \|\mathcal{A}(X_1 + X_2)\|_1 \leq \frac{1}{m} \|\mathcal{A}(X_1)\|_1 + \frac{1}{m} \|\mathcal{A}(X_2)\|_1 \\ &\leq U_{\mathcal{A}} \|X_1\|_F + U_{\mathcal{A}} \|X_2\|_F \leq \sqrt{2} U_{\mathcal{A}} \|X_1 + X_2\|_F \leq \sqrt{2} U_{\mathcal{A}} \epsilon. \end{aligned}$$

Thus

$$\frac{1}{m} \|\mathcal{A}(X)\|_1 \leq \frac{1}{m} \|\mathcal{A}(X_0)\|_1 + \frac{1}{m} \|\mathcal{A}(X - X_0)\|_1 \leq 2 + \epsilon_0 + \sqrt{2} U_{\mathcal{A}} \epsilon. \tag{2.7}$$

According to the definition of  $U_{\mathcal{A}}$ , (2.7) implies  $U_{\mathcal{A}} \leq 2 + \epsilon_0 + \sqrt{2} U_{\mathcal{A}} \epsilon$  and hence which implies that

$$U_{\mathcal{A}} \leq \frac{2 + \epsilon_0}{1 - \sqrt{2} \epsilon}.$$

We also have

$$\frac{1}{m} \|\mathcal{A}(X)\|_1 \geq \frac{1}{m} \|\mathcal{A}(X_0)\|_1 - \frac{1}{m} \|\mathcal{A}(X - X_0)\|_1 \geq 0.57 - \epsilon_0 - \sqrt{2} U_{\mathcal{A}} \epsilon \geq 0.57 - \epsilon_0 - \sqrt{2} \frac{2 + \epsilon_0}{1 - \sqrt{2} \epsilon} \epsilon.$$

Hence, we obtain that the following holds with probability at least  $1 - 2 \cdot \#\mathcal{N}_\epsilon \cdot \exp(-\frac{\epsilon_0}{16} m \epsilon_0^2)$

$$\left(0.57 - \epsilon_0 - \sqrt{2} \frac{2 + \epsilon_0}{1 - \sqrt{2} \epsilon} \epsilon\right) \|X\|_F \leq \frac{1}{m} \|\mathcal{A}(X)\|_1 \leq \left(\frac{2 + \epsilon_0}{1 - \sqrt{2} \epsilon}\right) \|X\|_F, \text{ for all } X \in \mathcal{X}.$$

Taking  $\epsilon = \epsilon_0 = 0.1$ , according to Lemma 2.3, we obtain  $\#\mathcal{N}_\epsilon \leq \left(\frac{90\sqrt{2}en}{k}\right)^{4k+2}$ . Thus when  $m \geq O(k \log(en/k))$ , we obtain that

$$0.12\|X\|_F \leq \frac{1}{m}\|\mathcal{A}(X)\|_1 \leq 2.45\|X\|_F, \quad \text{for all } X \in \mathcal{X}$$

holds with probability at least  $1 - 2\exp(-cm)$ .  $\square$

### 3. Proof of Theorem 1.3

In the following, we will use a technical tool based on results in [3,14] which provides convex  $k$ -sparse decompositions of certain signals in space.

**Lemma 3.1.** [3,14] *Suppose that  $\mathbf{v} \in \mathbb{R}^p$  satisfying  $\|\mathbf{v}\|_\infty \leq \theta$ ,  $\|\mathbf{v}\|_1 \leq s\theta$  where  $\theta > 0$  and  $s \in \mathbb{Z}_+$ . Then we have*

$$\mathbf{v} = \sum_{i=1}^N \lambda_i \mathbf{u}_i, \quad 0 \leq \lambda_i \leq 1, \quad \sum_{i=1}^N \lambda_i = 1,$$

where  $\mathbf{u}_i$  is  $s$ -sparse with  $(\text{supp}(\mathbf{u}_i)) \subset \text{supp}(\mathbf{v})$ , and

$$\|\mathbf{u}_i\|_1 = \|\mathbf{v}\|_1, \quad \|\mathbf{u}_i\|_\infty \leq \theta.$$

We also need the following lemma:

**Lemma 3.2.** *If  $\mathbf{x}, \mathbf{y} \in \mathbb{C}^d$ , and  $\langle \mathbf{x}, \mathbf{y} \rangle \geq 0$ , then*

$$\|\mathbf{x}\mathbf{x}^* - \mathbf{y}\mathbf{y}^*\|_F^2 \geq \frac{1}{2}\|\mathbf{x}\|_2^2\|\mathbf{x} - \mathbf{y}\|_2^2.$$

Similarly, we have

$$\|\mathbf{x}\mathbf{x}^* - \mathbf{y}\mathbf{y}^*\|_F^2 \geq \frac{1}{2}\|\mathbf{y}\|_2^2\|\mathbf{x} - \mathbf{y}\|_2^2.$$

**Proof.** We set  $a := \|\mathbf{x}\|_2$ ,  $b := \|\mathbf{y}\|_2$  and  $t := \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\|_2\|\mathbf{y}\|_2}$ . A simple calculation shows that

$$\|\mathbf{x}\mathbf{x}^* - \mathbf{y}\mathbf{y}^*\|_F^2 - \frac{1}{2}\|\mathbf{x}\|_2^2\|\mathbf{x} - \mathbf{y}\|_2^2 = h(a, b, t)$$

where

$$h(a, b, t) := a^4 + b^4 - 2(ab)^2t^2 - \frac{1}{2}a^2(a^2 + b^2 - 2abt).$$

Hence, to this end, it is enough to show that  $h(a, b, t) \geq 0$  provided  $a, b \geq 0$  and  $0 \leq t \leq 1$ . For any fixed  $a$  and  $b$ ,  $h(a, b, t)$  achieves the minimum for either  $t = 0$  or  $t = 1$ . For  $t = 0$ , we have

$$h(a, b, 0) = a^4 + b^4 - \frac{1}{2}a^4 - \frac{1}{2}a^2b^2 = \frac{1}{2}(a^2 - \frac{1}{2}b^2)^2 + \frac{7}{8}b^4 \geq 0. \quad (3.1)$$

When  $t = 1$ , we have

$$\begin{aligned} h(a, b, 1) &= a^4 + b^4 - \frac{1}{2}a^2(a^2 + b^2) - 2(ab)^2 + a^3b \\ &= (a - b)^2\left(\frac{1}{2}a^2 + b^2 + 2ab\right) \geq 0 \end{aligned} \quad (3.2)$$

Combining (3.1) and (3.2), we arrive at the conclusion.  $\square$

Now we have enough ingredients to prove Theorem 1.3.

**Proof of Theorem 1.3.** We assume that  $\mathbf{x}^\#$  is a solution to (1.2). Noting  $\exp(i\theta)\mathbf{x}^\#$  is also a solution to (1.2) for any  $\theta \in \mathbb{R}$ , in order to apply Lemma 3.2 in (3.10), we assume that

$$\langle \mathbf{x}^\#, \mathbf{x}_0 \rangle \in \mathbb{R} \quad \text{and} \quad \langle \mathbf{x}^\#, \mathbf{x}_0 \rangle \geq 0.$$

We consider the programming

$$\min_{X \in \mathbb{H}^{n \times n}} \|X\|_1 \quad \text{s.t.} \quad \|\mathcal{A}(X) - \mathbf{y}\|_2 \leq \epsilon, \quad \text{rank}(X) = 1. \tag{3.3}$$

Then a simple observation is that  $X^\#$  is the solution to (3.3) if and only if  $X^\# = \mathbf{x}^\#(\mathbf{x}^\#)^*$ .

Set  $X_0 := \mathbf{x}_0\mathbf{x}_0^*$  and  $H := X^\# - X_0 = \mathbf{x}^\#(\mathbf{x}^\#)^* - \mathbf{x}_0\mathbf{x}_0^*$ . Hence, we have to find an upper bound for  $\|H\|_F$ . Denote  $T_0 = \text{supp}(\mathbf{x}_0)$ . Set  $T_1$  as the index set which contains the indices of the  $ak$  largest elements of  $\mathbf{x}_{T_0^\complement}^\#$  in magnitude, and  $T_2$  contains the indices of the next  $ak$  largest elements, and so on. For simplicity, we set  $T_{01} := T_0 \cup T_1$  and  $\bar{H} := H_{T_{01}, T_{01}}$ , where  $H_{S,T}$  denotes the sub-matrix of  $H$  with the row set  $S$  and the column set  $T$ . We claim that

$$\|H\|_F \leq \|\bar{H}\|_F + \|H - \bar{H}\|_F \leq \left( \frac{1}{a} + \frac{4}{\sqrt{a}} + 1 \right) \|\bar{H}\|_F \leq \frac{\frac{1}{a} + \frac{4}{\sqrt{a}} + 1}{c - \frac{4C}{\sqrt{a}} - \frac{C}{a}} \frac{2\epsilon}{\sqrt{m}}, \tag{3.4}$$

which implies the conclusion (1.5). According to Lemma 3.2, we obtain that

$$\min_{c \in \mathbb{C}, |c|=1} \|c \cdot \mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \|\mathbf{x}^\# - \mathbf{x}_0\|_2 \leq \sqrt{2} \|H\|_F / \|\mathbf{x}_0\|_2 \leq \frac{\frac{1}{a} + \frac{4}{\sqrt{a}} + 1}{c - \frac{4C}{\sqrt{a}} - \frac{C}{a}} \frac{2\sqrt{2}\epsilon}{\sqrt{m}\|\mathbf{x}_0\|_2}.$$

We next turn to prove (3.4). The first inequality in (3.4) follows from

$$\|H - \bar{H}\|_F \leq \left( \frac{1}{a} + \frac{4}{\sqrt{a}} \right) \|\bar{H}\|_F \tag{3.5}$$

and the second inequality follows from

$$\|\bar{H}\|_F \leq \frac{1}{c - \frac{4C}{\sqrt{a}} - \frac{C}{a}} \frac{2\epsilon}{\sqrt{m}}. \tag{3.6}$$

To this end, it is enough to prove (3.5) and (3.6).

**Step 1:** We first present the proof of (3.5). A simple observation is that

$$\begin{aligned} \|H - \bar{H}\|_F &\leq \sum_{i \geq 2, j \geq 2} \|H_{T_i, T_j}\|_F + \sum_{i=0,1} \sum_{j \geq 2} \|H_{T_i, T_j}\|_F + \sum_{j=0,1} \sum_{i \geq 2} \|H_{T_i, T_j}\|_F \\ &= \sum_{i \geq 2, j \geq 2} \|H_{T_i, T_j}\|_F + 2 \sum_{i=0,1} \sum_{j \geq 2} \|H_{T_i, T_j}\|_F. \end{aligned} \tag{3.7}$$

We first consider the first term on the right-hand side of (3.7). Note that

$$\begin{aligned} \sum_{i \geq 2, j \geq 2} \|H_{T_i, T_j}\|_F &= \sum_{i \geq 2, j \geq 2} \|\mathbf{x}_{T_i}^\# \|_2 \cdot \|\mathbf{x}_{T_j}^\# \|_2 = \left( \sum_{i \geq 2} \|\mathbf{x}_{T_i}^\# \|_2 \right)^2 \leq \frac{1}{ak} \|\mathbf{x}_{T_0^\complement}^\# \|_1^2 \\ &= \frac{1}{ak} \|H_{T_0^\complement, T_0^\complement}\|_1 \leq \frac{1}{ak} \|H_{T_0, T_0}\|_1 \leq \frac{1}{a} \|H_{T_0, T_0}\|_F \leq \frac{1}{a} \|\bar{H}\|_F. \end{aligned} \tag{3.8}$$

Here, the first inequality follows from  $\|\mathbf{x}_{T_i}^\#\|_2 \leq \|\mathbf{x}_{T_{i-1}}^\#\|_1/\sqrt{ak}$ , for  $i \geq 2$ . The second inequality is based on  $\|H - H_{T_0, T_0}\|_1 \leq \|H_{T_0, T_0}\|_1$ . Indeed, according to  $\|X^\#\|_1 \leq \|X_0\|_1$ , we have

$$\|H - H_{T_0, T_0}\|_1 = \|X^\# - X_{T_0, T_0}^\#\|_1 \leq \|X_0\|_1 - \|X_{T_0, T_0}^\#\|_1 \leq \|X_0 - X_{T_0, T_0}^\#\|_1 = \|H_{T_0, T_0}\|_1.$$

We next turn to  $\sum_{i=0,1} \sum_{j \geq 2} \|H_{T_i, T_j}\|_F$ . Re-using  $\|\mathbf{x}_{T_j}^\#\|_2 \leq \|\mathbf{x}_{T_{j-1}}^\#\|_1/\sqrt{ak}$ , we have, for  $i \in \{0, 1\}$ ,

$$\sum_{j \geq 2} \|H_{T_i, T_j}\|_F = \|\mathbf{x}_{T_i}^\#\|_2 \cdot \sum_{j \geq 2} \|\mathbf{x}_{T_j}^\#\|_2 \leq \frac{1}{\sqrt{ak}} \|\mathbf{x}_{T_0^c}^\#\|_1 \|\mathbf{x}_{T_i}^\#\|_2 \leq \frac{1}{\sqrt{a}} \|\mathbf{x}_{T_i}^\#\|_2 \|\mathbf{x}_{T_0^c}^\# - \mathbf{x}_0\|_2. \tag{3.9}$$

The last inequality is based on  $\|\mathbf{x}^\#\|_1 \leq \|\mathbf{x}_0\|_1$ , which leads to

$$\|\mathbf{x}_{T_0^c}^\#\|_1 \leq \|\mathbf{x}_0\|_1 - \|\mathbf{x}_{T_0}^\#\|_1 \leq \|\mathbf{x}_{T_0}^\# - \mathbf{x}_0\|_1 \leq \sqrt{k} \|\mathbf{x}_{T_0}^\# - \mathbf{x}_0\|_2 \leq \sqrt{k} \|\mathbf{x}_{T_0^c}^\# - \mathbf{x}_0\|_2.$$

Substituting (3.8) and (3.9) into (3.7), we obtain that

$$\begin{aligned} \|H - \bar{H}\|_F &\leq \sum_{i \geq 2, j \geq 2} \|H_{T_i, T_j}\|_F + \sum_{i=0,1} \sum_{j \geq 2} \|H_{T_i, T_j}\|_F + \sum_{j=0,1} \sum_{i \geq 2} \|H_{T_i, T_j}\|_F \\ &\leq \frac{1}{a} \|\bar{H}\|_F + \frac{2\sqrt{2}}{\sqrt{a}} \|\mathbf{x}_{T_0^c}^\#\|_2 \|\mathbf{x}_{T_0^c}^\# - \mathbf{x}_0\|_2 \leq \left(\frac{1}{a} + \frac{4}{\sqrt{a}}\right) \|\bar{H}\|_F, \end{aligned} \tag{3.10}$$

where the second inequality is based on  $\|\mathbf{x}_{T_0}^\#\|_2 + \|\mathbf{x}_{T_1}^\#\|_2 \leq \sqrt{2} \|\mathbf{x}_{T_0^c}^\#\|_2$ , and the third inequality follows from Lemma 3.2.

**Step 2:** We next prove (3.6). Since

$$\|\mathcal{A}(H)\|_2 \leq \|\mathcal{A}(X^\#) - \mathbf{y}\|_2 + \|\mathcal{A}(X_0) - \mathbf{y}\|_2 \leq 2\epsilon,$$

we have

$$\frac{2\epsilon}{\sqrt{m}} \geq \frac{1}{\sqrt{m}} \|\mathcal{A}(H)\|_2 \geq \frac{1}{m} \|\mathcal{A}(H)\|_1 \geq \frac{1}{m} \|\mathcal{A}(\bar{H})\|_1 - \frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1. \tag{3.11}$$

In order to get a lower bound of  $\frac{1}{m} \|\mathcal{A}(\bar{H})\|_1 - \frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1$ , we bound  $\frac{1}{m} \|\mathcal{A}(\bar{H})\|_1$  from below and  $\frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1$  from above. As  $\text{rank}(\bar{H}) \leq 2$  and  $\|\bar{H}\|_{0,2} \leq (a+1)k$ , we obtain by RIP of  $\mathcal{A}$  that

$$\frac{1}{m} \|\mathcal{A}(\bar{H})\|_1 \geq c \|\bar{H}\|_F. \tag{3.12}$$

Since  $H - \bar{H}$  can be written as

$$H - \bar{H} = (H_{T_0, T_{01}^c} + H_{T_{01}^c, T_0}) + (H_{T_1, T_{01}^c} + H_{T_{01}^c, T_1}) + H_{T_{01}^c, T_{01}^c},$$

we have

$$\frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1 \leq \frac{1}{m} \|\mathcal{A}(H_{T_0, T_{01}^c} + H_{T_{01}^c, T_0})\|_1 + \frac{1}{m} \|\mathcal{A}(H_{T_1, T_{01}^c} + H_{T_{01}^c, T_1})\|_1 + \frac{1}{m} \|\mathcal{A}(H_{T_{01}^c, T_{01}^c})\|_1. \tag{3.13}$$

According to the RIP condition, for  $i \in \{0, 1\}$ , we have

$$\begin{aligned}
 \frac{1}{m} \|\mathcal{A}(H_{T_i, T_{01}^c} + H_{T_{01}^c, T_i})\|_1 &\leq \sum_{j \geq 2} \frac{1}{m} \|\mathcal{A}(H_{T_i, T_j} + H_{T_j, T_i})\|_1 \leq \sum_{j \geq 2} C \|H_{T_i, T_j} + H_{T_j, T_i}\|_F \\
 &\leq C \sum_{j \geq 2} (\|\mathbf{x}_{T_i}^\# (\mathbf{x}_{T_j}^\#)^*\|_F + \|\mathbf{x}_{T_j}^\# (\mathbf{x}_{T_i}^\#)^*\|_F) = 2C \sum_{j \geq 2} \|\mathbf{x}_{T_i}^\#\|_2 \|\mathbf{x}_{T_j}^\#\|_2 \\
 &\leq \frac{2C}{\sqrt{a}} \|\mathbf{x}_{T_i}^\#\|_2 \|\mathbf{x}_{T_{01}^c}^\# - \mathbf{x}_0\|_2,
 \end{aligned} \tag{3.14}$$

where the first inequality follows from

$$H_{T_i, T_{01}^c} + H_{T_{01}^c, T_i} = \sum_{j \geq 2} (H_{T_i, T_j} + H_{T_j, T_i}) = \sum_{j \geq 2} (\mathbf{x}_{T_i}^\# (\mathbf{x}_{T_j}^\#)^* + \mathbf{x}_{T_j}^\# (\mathbf{x}_{T_i}^\#)^*)$$

and the last inequality is obtained as in (3.9). To bound  $\frac{1}{m} \|\mathcal{A}(H_{T_{01}^c, T_{01}^c})\|_1$ , note that

$$H_{T_{01}^c, T_{01}^c} = \mathbf{x}_{T_{01}^c}^\# (\mathbf{x}_{T_{01}^c}^\#)^*$$

with  $\|\mathbf{x}_{T_{01}^c}^\#\|_\infty \leq \|\mathbf{x}_{T_1}^\#\|_1 / (ak)$ . Set  $\theta := \max\{\|\mathbf{x}_{T_1}^\#\|_1 / (ak), \|\mathbf{x}_{T_{01}^c}^\#\|_1 / (ak)\}$ . We assume that  $\Phi := \text{Diag}(Ph(\mathbf{x}_{T_{01}^c}^\#))$  is the diagonal matrix with diagonal elements being the phase of  $\mathbf{x}_{T_{01}^c}^\#$ , i.e.,  $\Phi^{-1} \mathbf{x}_{T_{01}^c}^\#$  is a real vector. According to Lemma 3.1, we have

$$\Phi^{-1} \mathbf{x}_{T_{01}^c}^\# = \sum_{i=1}^N \lambda_i \mathbf{u}_i, \quad 0 \leq \lambda_i \leq 1, \quad \sum_{i=1}^N \lambda_i = 1,$$

where  $\mathbf{u}_i$  is  $ak$ -sparse, and

$$\|\mathbf{u}_i\|_1 = \|\mathbf{x}_{T_{01}^c}^\#\|_1, \quad \|\mathbf{u}_i\|_\infty \leq \theta,$$

which leads to

$$\|\mathbf{u}_i\|_2 \leq \sqrt{\|\mathbf{u}_i\|_1 \|\mathbf{u}_i\|_\infty} \leq \sqrt{\theta \|\mathbf{x}_{T_{01}^c}^\#\|_1}.$$

If  $\theta = \|\mathbf{x}_{T_1}^\#\|_1 / (ak)$ , we have

$$\begin{aligned}
 \|\mathbf{u}_i\|_2 &\leq \sqrt{\frac{\|\mathbf{x}_{T_1}^\#\|_1 \|\mathbf{x}_{T_{01}^c}^\#\|_1}{ak}} = \sqrt{\frac{\|H_{T_1, T_{01}^c}\|_1}{ak}} \\
 &\leq \sqrt{\frac{\|H - H_{T_0, T_0}\|_1}{ak}} \leq \sqrt{\frac{\|H_{T_0, T_0}\|_1}{ak}} \leq \sqrt{\frac{\|H_{T_0, T_0}\|_F}{a}} \leq \sqrt{\frac{\|\bar{H}\|_F}{a}}.
 \end{aligned}$$

If  $\theta = \|\mathbf{x}_{T_{01}^c}^\#\|_1 / (ak)$ , we have

$$\begin{aligned}
 \|\mathbf{u}_i\|_2 &\leq \sqrt{\frac{\|\mathbf{x}_{T_{01}^c}^\#\|_1 \|\mathbf{x}_{T_{01}^c}^\#\|_1}{ak}} = \sqrt{\frac{\|H_{T_{01}^c, T_{01}^c}\|_1}{ak}} \\
 &\leq \sqrt{\frac{\|H - H_{T_0, T_0}\|_1}{ak}} \leq \sqrt{\frac{\|H_{T_0, T_0}\|_1}{ak}} \leq \sqrt{\frac{\|H_{T_0, T_0}\|_F}{a}} \leq \sqrt{\frac{\|\bar{H}\|_F}{a}}.
 \end{aligned}$$

Thus we can obtain that

$$\|\mathbf{u}_i\|_2 \leq \sqrt{\frac{\|\bar{H}\|_F}{a}}, \text{ for } i = 1, \dots, N. \tag{3.15}$$

Since

$$\begin{aligned} H_{T_{01}^c, T_{01}^c} &= \mathbf{x}_{T_{01}^c}^\# (\mathbf{x}_{T_{01}^c}^\#)^* = \left( \sum_{i=1}^N \lambda_i \Phi \mathbf{u}_i \right) \left( \sum_{i=1}^N \lambda_i \Phi \mathbf{u}_i \right)^* \\ &= \sum_{i < j} \lambda_i \lambda_j \Phi (\mathbf{u}_i \mathbf{u}_j^* + \mathbf{u}_j \mathbf{u}_i^*) \Phi^{-1} + \sum_i \lambda_i^2 \Phi \mathbf{u}_i \mathbf{u}_i^* \Phi^{-1}, \end{aligned}$$

based on the RIP condition, we can obtain that

$$\begin{aligned} \frac{1}{m} \|\mathcal{A}(H_{T_{01}^c, T_{01}^c})\|_1 &\leq \sum_{i < j} C \lambda_i \lambda_j \|(\mathbf{u}_i \mathbf{u}_j^* + \mathbf{u}_j \mathbf{u}_i^*)\|_F + \sum_i C \lambda_i^2 \|\mathbf{u}_i \mathbf{u}_i^*\|_F \\ &\leq \sum_{i < j} 2C \lambda_i \lambda_j \|\mathbf{u}_i\|_2 \|\mathbf{u}_j\|_2 + \sum_i C \lambda_i^2 \|\mathbf{u}_i\|_2^2 \\ &\leq C \frac{\|\bar{H}\|_F}{a} \left( \sum_i \lambda_i \right)^2 = C \frac{\|\bar{H}\|_F}{a}, \end{aligned} \tag{3.16}$$

where the third line follows from (3.15). Now combining (3.14) and (3.16), we obtain that

$$\begin{aligned} \frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1 &\leq \frac{1}{m} \|\mathcal{A}(H_{T_0, T_{01}^c} + H_{T_{01}^c, T_0})\|_1 + \frac{1}{m} \|\mathcal{A}(H_{T_1, T_{01}^c} + H_{T_{01}^c, T_1})\|_1 + \frac{1}{m} \|\mathcal{A}(H_{T_{01}^c, T_{01}^c})\|_1 \\ &\leq \frac{2C}{\sqrt{a}} \|\mathbf{x}_{T_0}^\#\|_2 \|\mathbf{x}_{T_{01}^c}^\# - \mathbf{x}_0\|_2 + \frac{2C}{\sqrt{a}} \|\mathbf{x}_{T_1}^\#\|_2 \|\mathbf{x}_{T_{01}^c}^\# - \mathbf{x}_0\|_2 + C \frac{\|\bar{H}\|_F}{a} \\ &\leq \frac{2\sqrt{2}C}{\sqrt{a}} \|\mathbf{x}_{T_{01}^c}^\#\|_2 \|\mathbf{x}_{T_{01}^c}^\# - \mathbf{x}_0\|_2 + C \frac{\|\bar{H}\|_F}{a} \\ &\leq C \left( \frac{4}{\sqrt{a}} + \frac{1}{a} \right) \|\bar{H}\|_F. \end{aligned} \tag{3.17}$$

The last inequality uses Lemma 3.2. Based on (3.12), (3.17) and (3.11), we obtain that

$$\begin{aligned} \frac{2\epsilon}{\sqrt{m}} &\geq \frac{1}{m} \|\mathcal{A}(\bar{H})\|_1 - \frac{1}{m} \|\mathcal{A}(H - \bar{H})\|_1 \\ &\geq c \|\bar{H}\|_F - C \left( \frac{4}{\sqrt{a}} + \frac{1}{a} \right) \|\bar{H}\|_F = \left( c - \frac{4C}{\sqrt{a}} - \frac{C}{a} \right) \|\bar{H}\|_F. \end{aligned}$$

According to the condition (1.4), it implies that

$$\|\bar{H}\|_F \leq \frac{1}{c - \frac{4C}{\sqrt{a}} - \frac{C}{a}} \frac{2\epsilon}{\sqrt{m}}.$$

Thus, we arrive at the conclusion (3.6).  $\square$

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